

TECHNICAL

# DESCRIPTION

**MSX-E3011 and MSX-E3021**  
Ethernet analog input system



### Product information

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## Warning!

The following risks result from the improper implementation of the Ethernet system and from use contrary to the regulations:



**Personal injury**



**Damage to the Ethernet system, the PC and peripherals**



**Pollution of the environment.**

- Protect yourself, others and the environment!
- Read the safety precautions (yellow leaflet) carefully!  
If this leaflet is not enclosed with the documentation, please contact us and ask for it.
- Observe the instructions of this manual!  
Make sure that you do not forget or skip any step!  
We are not liable for damages resulting from the wrong use of the Ethernet system.
- Pay attention to the following symbols:



### NOTICE!

Designates hints and other useful information.



### NOTICE!

Designates a possibly dangerous situation.

If the instructions are ignored, the Ethernet system, the PC and/or peripherals may be **destroyed**.



### WARNING!

Designates a possibly dangerous situation.

If the instructions are ignored, the Ethernet system, the PC and/or peripherals may be **destroyed** and persons may be **endangered**.

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## Chapter overview

In this manual, you will find the following information:

Chapter	Content
1	Important information on the application, the user and on handling the MSX-E system as well as safety precautions
2	Brief description of the MSX-E system (functions, features, block diagram)
3	Function description (analog inputs) including pin assignment
4	Description of the function-specific pages of the MSX-E web interface plus information on the data format
5	Description of the acquisition modes (Auto-refresh and Sequence mode)
6	List of technical data and limit values of the MSX-E system
7	Appendix with glossary and index
8	Contact and support address

# 1 Definition of application, user, handling

## 1.1 Definition of application

### 1.1.1 Intended use

The Ethernet systems **MSX-E3011** and **MSX-E3021** for analog input are intended for the connection to a network, which is used as electrical equipment for measurement, control and laboratory pursuant to the norm EN 61010-1 (IEC 61010-1).

### 1.1.2 Usage restrictions

The Ethernet systems **MSX-E3011** and **MSX-E3021** must not be used as safety-related parts (SRP).

The Ethernet systems **MSX-E3011** and **MSX-E3021** must not be used for safety-related functions.

The Ethernet systems **MSX-E3011** and **MSX-E3021** must not be used in potentially explosive atmospheres.

The Ethernet systems **MSX-E3011** and **MSX-E3021** must not be used as electrical equipment according to the Low Voltage Directive 2006/95/EC.

### 1.1.3 Limits of use

All safety information and the instructions in the manuals must be followed to ensure proper intended use.

Uses of the Ethernet system beyond these specifications are considered as improper use.

The manufacturer is not liable for damages resulting from improper use.

The Ethernet system must remain in its anti-static packaging until it is installed.

Please do not delete the identification numbers of the Ethernet system or the warranty claim will be invalid.

## 1.2 Safety precautions

### 1.2.1 Current sources

All connected devices must be supplied from current sources that comply with SELV according to IEC 60950 or EN 60950; or PELV according to IEC 60204-1 or EN 60204-1.

### 1.2.2 Degrees of protection



#### NOTICE!

The protection according to the defined degree of protection (see Chapter 6.4) is only given if the openings are protected with adequate protection caps or connectors.

If you are not sure, please contact us:

Phone: +49 7229 1847-0

E-mail: [info@addi-data.com](mailto:info@addi-data.com)

### 1.2.3 Cables

The cables must be installed safely against mechanical load.

### 1.2.4 Housing

The housing must not be opened. It may only be opened by persons who have been authorised by ADDI-DATA.

## 1.3 User

### 1.3.1 Qualification

Only persons trained in electronics are entitled to perform the following works:

- Installation
- Commissioning
- Use
- Maintenance.

### 1.3.2 Country-specific regulations

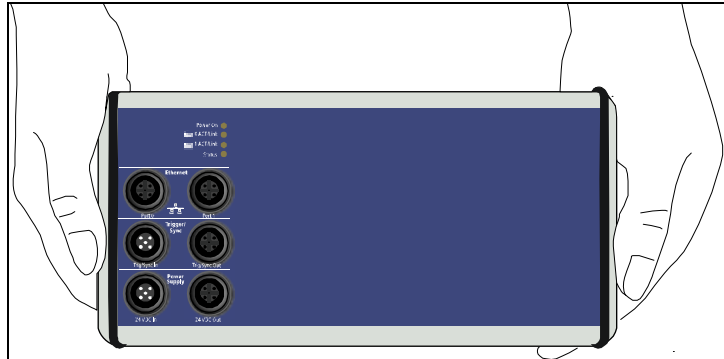
Do observe the country-specific regulations regarding

- the prevention of accidents
- electrical and mechanical installations
- Electromagnetic compatibility (EMC).



## 1.4 Handling of the Ethernet system

Fig. 1-1: Correct handling



- Hold the Ethernet system by the bottom and the grey sides.
- Do not hold the Ethernet system by the connectors!

## 1.5 Questions and updates

If you have any questions, you can send them to us by e-mail or call us:

E-mail: [info@addi-data.com](mailto:info@addi-data.com)

Phone: +49 7229 1847-0.

### Manual and software download from the Internet

The latest versions of the technical manual and the standard software for the Ethernet systems **MSX-E3011** and **MSX-E3021** can be downloaded for free at: [www.addi-data.com](http://www.addi-data.com)



### NOTICE!

Before using the Ethernet system and in case of malfunction during operation, check if there is an update (manual, driver, firmware) available. Current data can be found on our website or contact us directly.

## 2 Brief description

### 2.1 Functions and features

Each of the intelligent Ethernet systems **MSX-E3011** and **MSX-E3021** has 16 differential analog inputs with 16-bit resolution and a throughput rate of 25 kHz per channel.

In addition, the Ethernet system **MSX-E3021** has a buffered real-time clock, which keeps the system time even in case of power loss, and an extended memory of 4 GB for storing the measured values. Thus, the system is perfectly suited for long-term measurements.

By means of an external trigger, analog inputs on multiple systems can be updated simultaneously (synchronisation). The systems can be configured over either the integrated web interface or SOAP or Modbus commands. These interfaces also enable sensor data to be accessed.

Via an integrated Ethernet switch, the systems can be cascaded with other MSX-E systems. This also applies to the voltage supply and the trigger/synchro line, which facilitates wiring between the single systems.

The Ethernet systems are mounted in a robust EMC-protected metal housing, which complies with the degree of protection IP 65. In this way, the Ethernet systems are able to cope with daily stresses and strains such as current peaks, vibrations, dirt or extreme temperatures. Moreover, they can be used in the extended operating temperature range from -40 °C to +85 °C and are equipped with numerous protective circuits. The "Status" LED provides for a quick and easy error diagnosis.

The electronics are no longer in the computer itself but in an external housing connected to the computer via Ethernet. As the Ethernet systems are attached in direct vicinity of the sensor, the function of the latter is no longer affected by long cables. The length of the (Ethernet) connection cable from the Ethernet system to the computer may be up to 150 m. The systems must be supplied with external voltage (24 V).

#### Features:

- 16 analog inputs, differential, 16-bit
- **MSX-E3021:** extended memory (4 GB), buffered real-time clock
- Analog input: can be controlled by means of an external trigger (digital 24 V trigger input)
- Web interface to configure, control and monitor the analog input
- Data access via SOAP or Modbus (always TCP or UDP)
- Optical isolation
- Degree of protection: IP 65
- Cascadable; synchronisation in the µs range
- Extended operating temperature range from -40 °C to +85 °C (**MSX-E3021:** on request)

## 2.2 Block diagram

Fig. 2-1: MSX-E3011: Block diagram

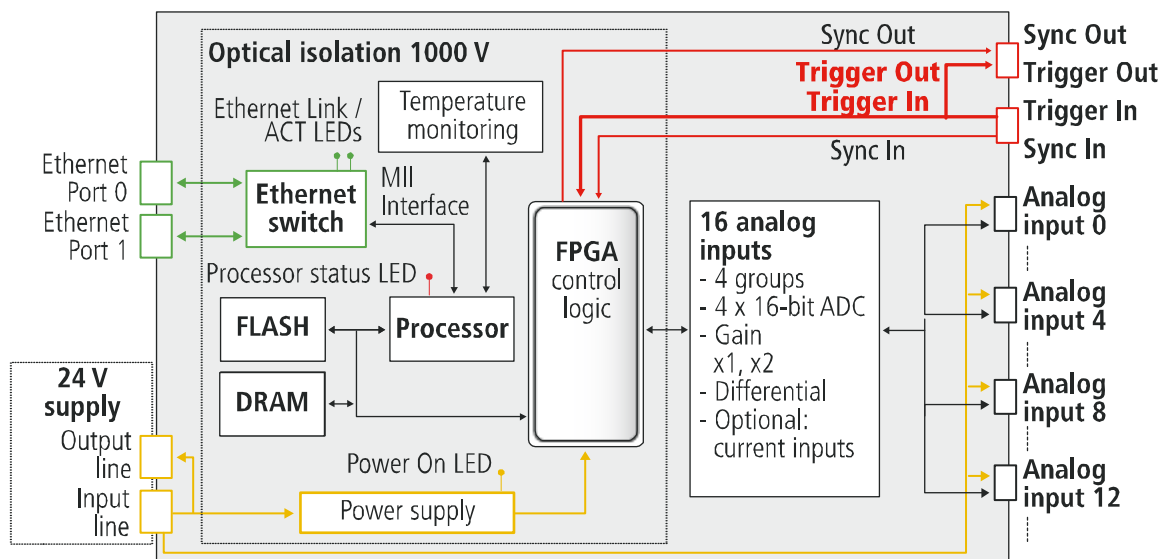
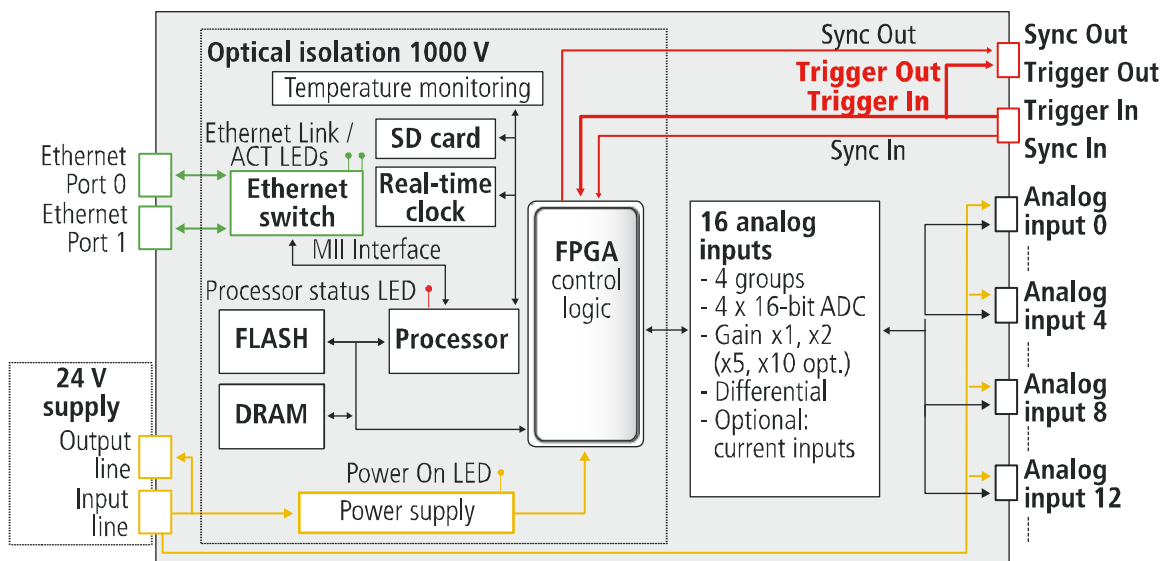


Fig. 2-2: MSX-E3021: Block diagram



### 3 Function description: Analog inputs

Each of the Ethernet systems **MSX-E3011** and **MSX-E3021** has 16 analog inputs for sensors, which are divided into four groups.

An A/D converter and a 4-channel multiplexer are assigned to each group of inputs. As an option, the individual groups may be composed of either voltage or current inputs. The data is acquired simultaneously in all groups.

In unipolar mode, the resolution is reduced from 16-bit to 15-bit.



#### NOTICE!

The current inputs can only be used in unipolar mode!

#### 3.1 Pin assignment

To each M12 female connector, one sensor can be connected.

One analog input consists of input + and input -. Optionally, a 24 V voltage is available to supply a sensor if required.

**Table 3-1: Pin assignment: Analog inputs**

Pin No.	Female connector, 5-pin, M12	Cable (black)
		Lead colour
1	+24 V	brown
2	Diff. input -	white
3	GND <sup>1</sup>	blue
4	Diff. input +	black
5	not connected	grey

<sup>1</sup> To use the inputs as single-ended inputs, pins 2 and 3 have to be connected externally with each other.

## 4 Web interface: Quick access to the MSX-E system

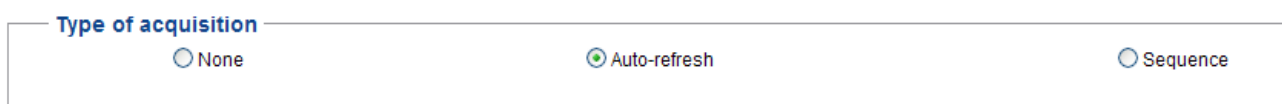
### 4.1 “I/O Configuration”

In this manual, the function-specific pages of the **MSX-E3011** or **MSX-E3021** web interface, which are located under the menu item “I/O Configuration”, are described.

For further information on the MSX-E web interface, please refer to the general manual of the MSX-E systems (see PDF link).

#### 4.1.1 Menu item “Analog inputs”

**Fig. 4-1: Analog inputs: Type of acquisition**



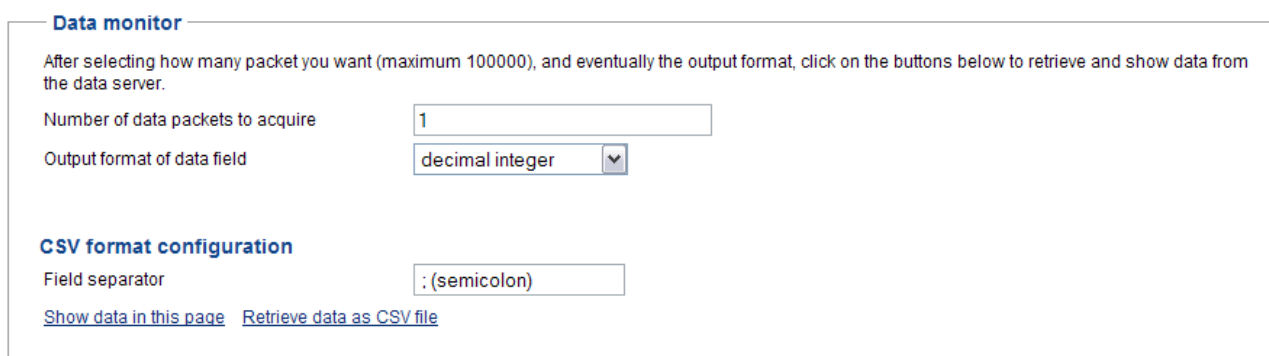
**Type of acquisition**

☐ None ☒ Auto-refresh ☐ Sequence

For the acquisition, the Auto-refresh mode and the Sequence mode are available. A detailed description of these modes can be found in Chapter 5 of this manual.

#### 4.1.2 Menu item “Monitor”

**Fig. 4-2: Monitor: Data monitor**



**Data monitor**

After selecting how many packet you want (maximum 100000), and eventually the output format, click on the buttons below to retrieve and show data from the data server.

Number of data packets to acquire

Output format of data field

**CSV format configuration**

Field separator

[Show data in this page](#) [Retrieve data as CSV file](#)

The acquired data can be displayed either directly on the web interface or in a CSV file. For this, the number of data packets and the output format of the data fields have to be defined.

Fig. 4-3: Monitor: Configuration details

Configuration details		
Conversion time		
conversion time	10	
Unit	microsecond	
Configuration of selected channel		
1	Bipolar	gain 1
Average mode		
Average mode	none	
Average value	1	
Trigger configuration		
Trigger source	disabled	

Also under this menu item, information on the current configuration as well as on data packets from the data server is listed.

Fig. 4-4: “Monitor”: Data packets

Additional information in data packet	
none	
Structure of binary data packets sent by the data server	
Field	Size (bytes)
counter	4
channel 1	4
sum	8

**Data format**

In Auto-refresh mode, the following data format applies:

**Table 4-1: Auto-refresh mode: Data format**

<b>tv_sec</b>	<b>tv_usec</b>	<b>Auto-refresh counter</b>	<b>Auto-refresh data</b>
4 bytes	4 bytes	4 bytes	4 bytes x amount of data
Time stamp (in s) low (if data format has time stamp)	Time stamp (in $\mu$ s) high (if data format has time stamp)	always available	The amount of data depends on the Auto-refresh mask.

In Sequence mode, the data format is as follows:

**Table 4-2: Sequence mode: Data format**

<b>tv_sec</b>	<b>tv_usec</b>	<b>Sequence counter</b>	<b>Sequence data</b>
4 bytes	4 bytes	4 bytes	4 bytes x amount of data
Time stamp (in s) low (if data format has time stamp)	Time stamp (in $\mu$ s) high (if data format has time stamp)	Sequence counter (if data format has Sequence counter)	The amount of data depends on the Sequence channel list.

To both modes applies:

Data format = without conversion into an analog value

Data x	32-bit digital value
--------	----------------------

Data format = with conversion into an analog value

Data x	32-bit floating point value (analog value) in V/A
--------	--

For more information on the data format, see Chapter 5.3.7.

## 5 Acquisition modes

This chapter exemplifies how to configure and start an acquisition via the web interface of the Ethernet system **MSX-E3011** or **MSX-E3021**. Moreover, you can use Modbus or SOAP functions (see MSX-E CD or driver download on the ADDI-DATA website) to perform these steps.

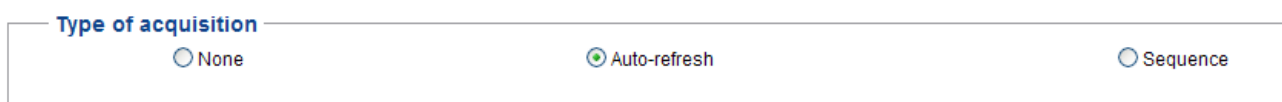
### 5.1 Auto-refresh mode

In Auto-refresh mode, one or more channels can be acquired. It is possible to start the acquisition by means of a trigger. Directly on the MSX-E system, an average value can be calculated.

- On the web interface, from the menu on the left, under “I/O Configuration”, select the menu item “Analog inputs”.

#### 5.1.1 “Type of acquisition”

Fig. 5-1: Analog inputs: Type of acquisition



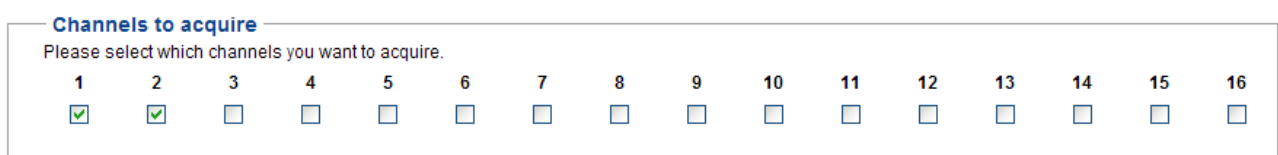
Type of acquisition

☐ None ☒ Auto-refresh ☐ Sequence

- In the section “Type of acquisition”, select the acquisition mode “Auto-refresh”.

#### 5.1.2 “Channels to acquire”

Fig. 5-2: Analog inputs: Channels to acquire



Channels to acquire

Please select which channels you want to acquire.

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

- In the section “Channels to acquire”, select the channels you want to acquire.



### 5.1.3 “Average setup” (average value calculation)

**Fig. 5-3: Auto-refresh mode: “Average setup”**

**Average setup**

- Average value computation **per channel**  
Each channel is acquired x times to compute an average value for the channel.
- Average value computation **per sequence**  
All sequences are acquired x times to compute an average value per channel.

Average mode: 
Average value:

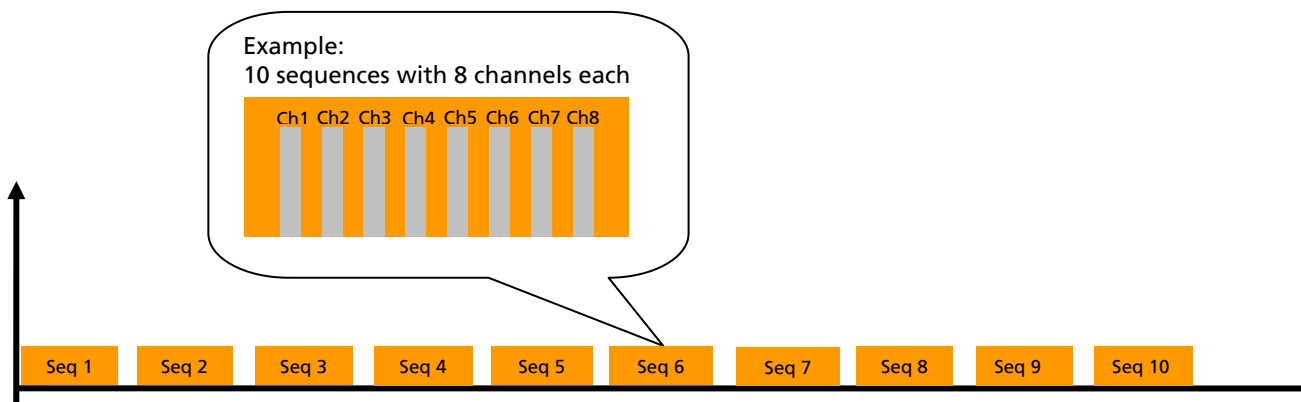
The MSX-E system is capable of calculating an average value for each channel. In the field “Average value”, you have to enter the number of acquisitions after which this value should be calculated.

Acquisition “per sequence” means that all selected channels are acquired simultaneously. If an acquisition “per channel” is to take place, the selected channels are acquired individually.

#### a) Acquisition per sequence

Example: The MSX-E system acquires channels 1 to 8. “Number of acquisitions” contains the value 10. This means that ten sequences run down, with each sequence consisting of eight channels to be acquired.

**Fig. 5-4: Auto-refresh mode: Acquisition per sequence**



After these ten sequences have run down, the MSX-E system performs the following calculation:

Average value of channel 1  
 $= (\text{sequence 1, value of channel 1} + \text{sequence 2, value of channel 1} + \dots + \text{sequence 10, value of channel 1}) / 10$

Average value of channel 2  
 $= (\text{sequence 1, value of channel 2} + \text{sequence 2, value of channel 2} + \dots + \text{sequence 10, value of channel 2}) / 10$

...

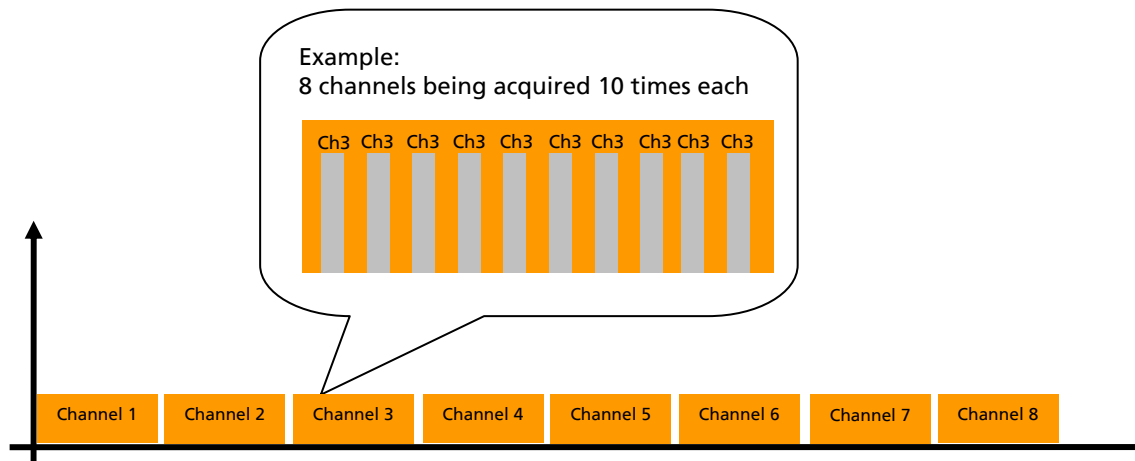
Average value of channel 8  
 $= (\text{sequence 1, value of channel 8} + \text{sequence 2, value of channel 8} + \dots + \text{sequence 10, value of channel 8}) / 10$

The network client will not receive ten data packets with eight values in each packet, but only one data packet with the average values from channels 1 to 8.

### b) Acquisition per channel

Example: The MSX-E system acquires channels 1 to 8. "Number of acquisitions" contains the value 10. This means that each of the eight channels is acquired ten times.

**Fig. 5-5: Auto-refresh mode: Acquisition per channel**



After all of the eight channels have been acquired, the MSX-E system performs the following calculation:

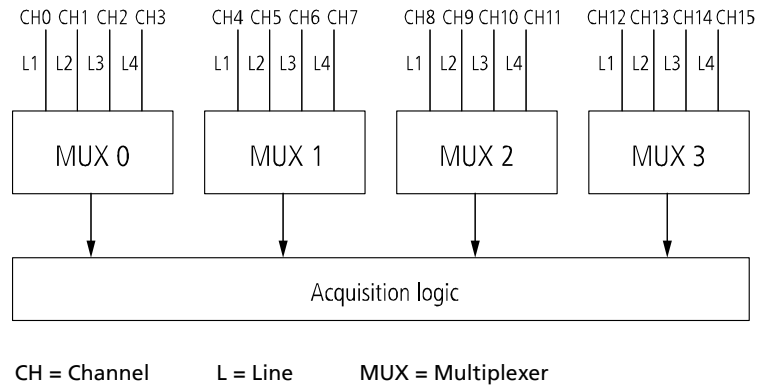
Average value of channel 1  
 $= (\text{value of channel 1} + \text{value of channel 1} + \dots + \text{value of channel 1}) / 10$   
 Average value of channel 2  
 $= (\text{value of channel 2} + \text{value of channel 2} + \dots + \text{value of channel 2}) / 10$   
 ...  
 Average value of channel 8  
 $= (\text{value of channel 8} + \text{value of channel 8} + \dots + \text{value of channel 8}) / 10$

The network client will not receive eight data packets with ten values in each packet, but only one data packet with the average values from channels 1 to 8.

### 5.1.4 Exceptions with the MSX-E3011 or MSX-E3021

As already mentioned in Chapter 3, the **MSX-E3011** or **MSX-E3021** has four 4-channel multiplexers. Consequently, the selected channels are not always acquired simultaneously or individually in an acquisition per sequence or per channel.

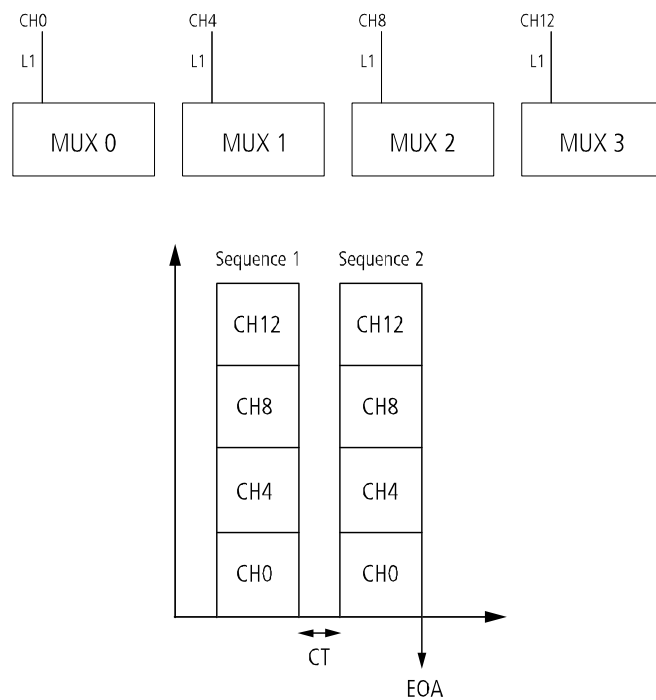
The reason for this is that e.g. line 1 of multiplexer 1 is connected in parallel to line 1 of each of the other three multiplexers.



The following examples illustrate the two acquisition modes with multiplexer lines connected in parallel or not.

### Example 1: Acquisition per sequence

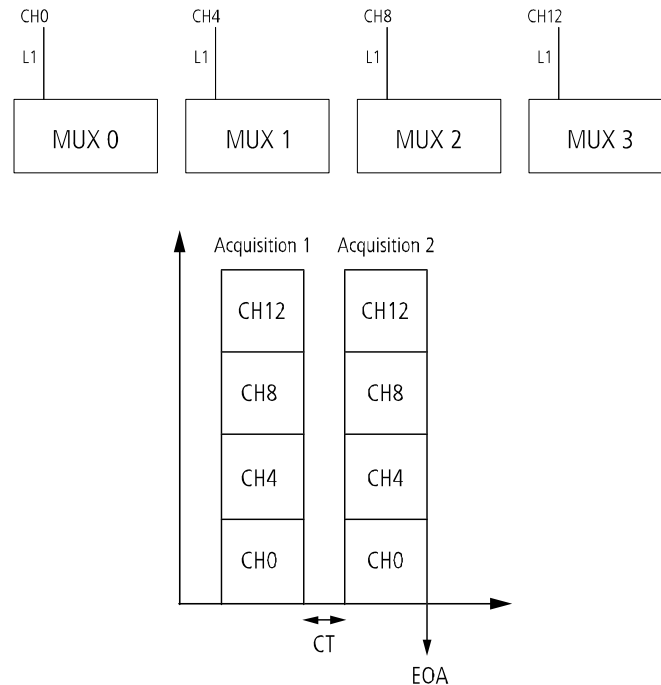
The MSX-E system acquires four channels. The corresponding multiplexer lines are connected in parallel. "Average value" contains the value 2.



In this example, the acquisition takes place in the usual manner, i.e. as described in Chapter 5.1.3.

**Example 2: Acquisition per channel**

The MSX-E system acquires four channels. The corresponding multiplexer lines are connected in parallel. "Average value" contains the value 2.

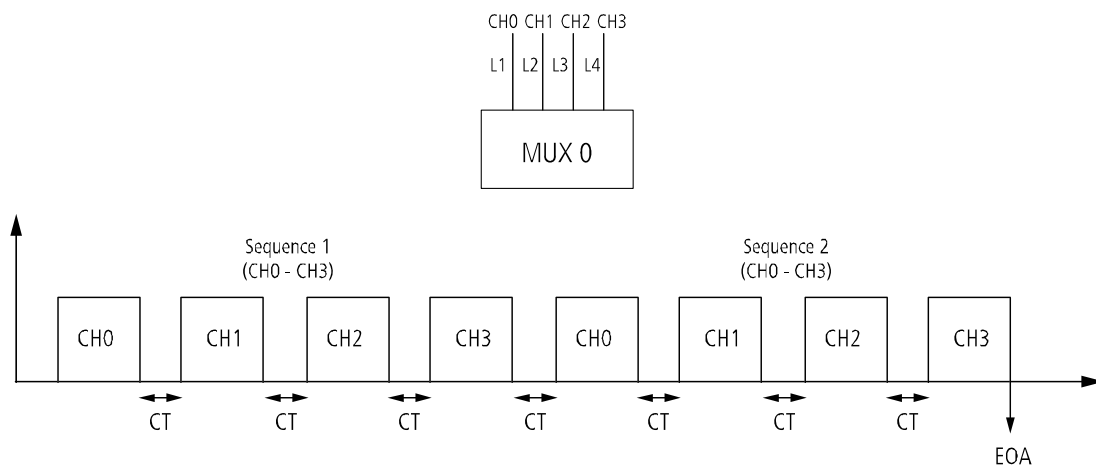


CT = Settling time      EOA = End of acquisition (average value is sent)

As there is no difference between examples 1 and 2 in this case, the same values as in example 1 are acquired.

**Example 3: Acquisition per sequence**

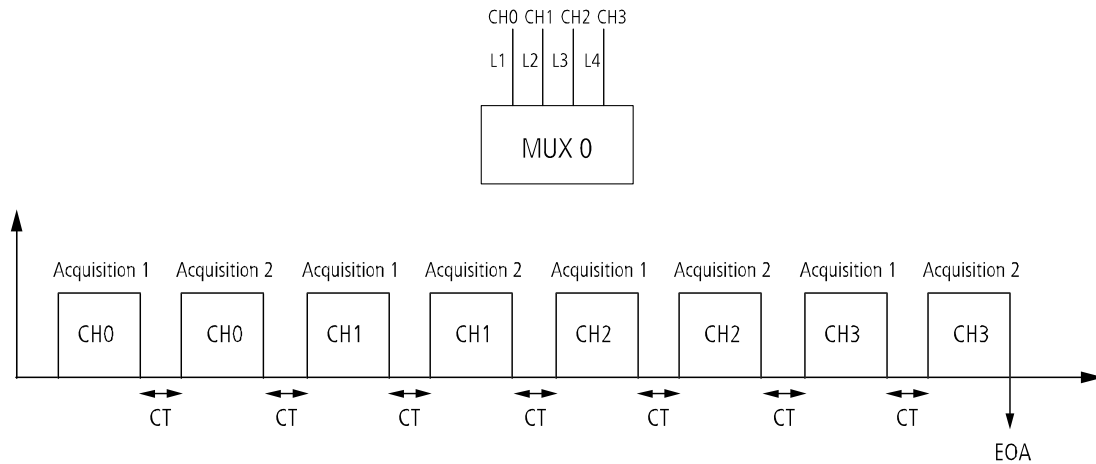
The MSX-E system acquires four channels. The corresponding multiplexer lines are not connected in parallel. "Average value" contains the value 2.



CT = Settling time      EOA = End of acquisition (average value is sent)

**Example 4: Acquisition per channel**

The MSX-E system acquires four channels. The corresponding multiplexer lines are not connected in parallel. "Average value" contains the value 2.

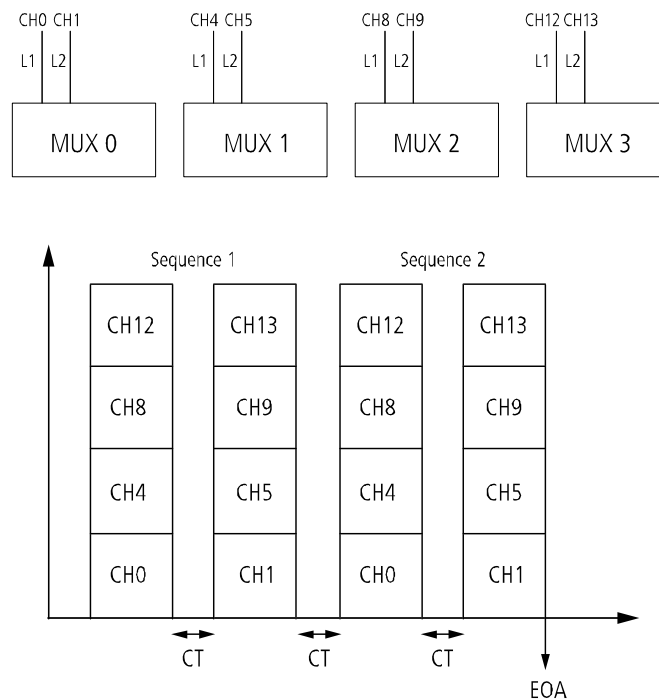


CT = Settling time      EOA = End of acquisition (average value is sent)

In this example, the acquisition takes place in the usual manner, i.e. as described in Chapter 5.1.3.

**Example 5: Acquisition per sequence**

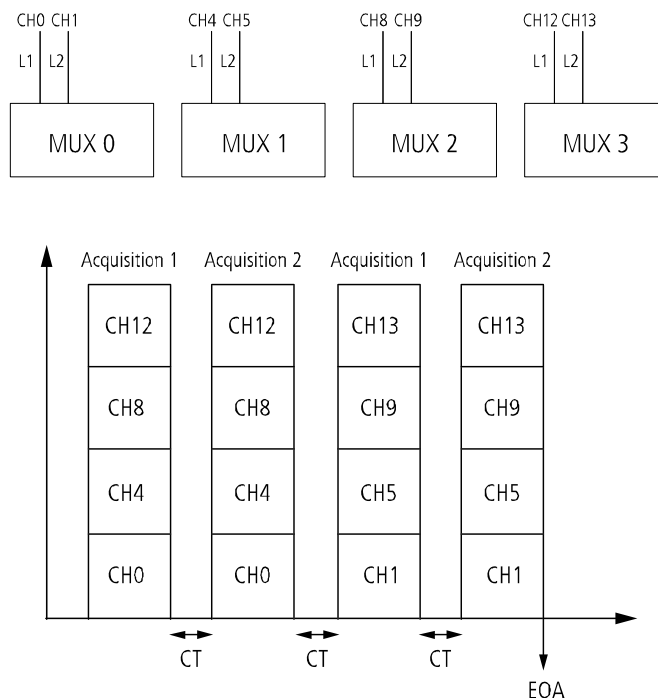
The MSX-E system acquires eight channels. The corresponding multiplexer lines 1 or 2 are connected in parallel. "Average value" contains the value 2.



CT = Settling time      EOA = End of acquisition (average value is sent)

**Example 6: Acquisition per channel**

The MSX-E system acquires eight channels. The corresponding multiplexer lines 1 or 2 are connected in parallel. "Average value" contains the value 2.



CT = Settling time      EOA = End of acquisition (average value is sent)

## 5.2 Sequence mode

The Sequence mode enables you to acquire one or more channels. The acquisition can be started by a trigger. There is a definable delay between the individual sequences.

- On the web interface, from the menu on the left, under "I/O Configuration", select the menu item "Analog inputs".

### 5.2.1 "Type of acquisition"

**Fig. 5-6: Analog inputs: Type of acquisition**

Type of acquisition

☐ None
 ☐ Auto-refresh
 ☒ Sequence

- In the section "Type of acquisition", select the acquisition mode "Sequence".

## 5.2.2 “Channels”

**Fig. 5-7: Acquisition: Channels**

**Channels**  
Please choose the serie of channels to acquire.

**Notes**

- A void channel entry in the sequence is simply ignored
- A sequence can acquire max. 16 channels (this does not depend on the number of physical channels the module actually has)
- A sequence may acquire the same channel several times.

16
5
3
11

sequence: **16 5 3 11**

■ In the section “Channels”, select the channels you want to acquire.

You can define the order of the channels. A channel can be acquired several times per sequence.

## 5.2.3 “Delay” (wait time)

**Fig. 5-8: Analog inputs: Delay**

**Delay**

**Modes**

- Mode 1: the delay defines the time between the begin of each sequence
- Mode 2: the delay defines the time between the end of a sequence and the begin of the next one

**Notes**

- When Mode 1 is selected, the field *delay value* must be superior or equal to the *minimal acquisition time*
- In Mode 2 there are no constraints on the delay value.

mode	time unit	delay value	minimal delay value
none	us	us	> us

In the “Delay” section, you can define the wait time between the individual sequences. There are two modes, which are explained below.

With “time unit”, you can select the unit of the delay ( $\mu$ s, ms or s). Enter the value of the delay in the field “Delay value”. The minimal delay value is displayed in the field behind.

**a) Mode 1**

The time between the start of two subsequent sequences is defined as the delay.

**Fig. 5-9: “Delay”: Mode 1**

Delay

**Modes**

- Mode 1: the delay defines the time between the begin of each sequence
- Mode 2: the delay defines the time between the end of a sequence and the begin of the next one

**Notes**

- When Mode 1 is selected, the field *delay value* must be superior or equal to the *minimal acquisition time*
- In Mode 2 there are no constraints on the delay value.

mode

1

time unit

ms

delay value

300

 ms

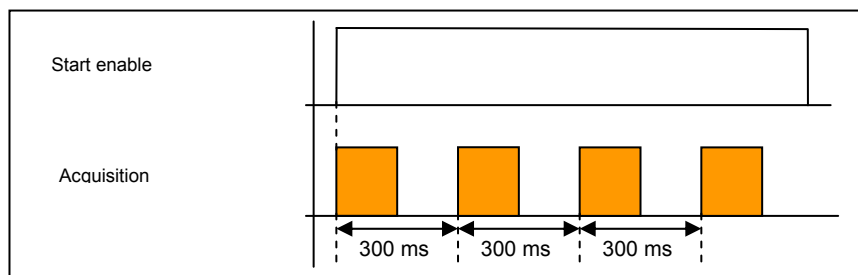
minimal delay value

> 0

 ms

**Example**

After the start of the acquisition (see Fig. 5-12), the delay between the start of the individual sequences is 300 ms.

**b) Mode 2**

The time between the end of a sequence and the start of the subsequent sequence is defined as the delay.

**Fig. 5-10: “Delay”: Mode 2**

Delay

**Modes**

- Mode 1: the delay defines the time between the begin of each sequence
- Mode 2: the delay defines the time between the end of a sequence and the begin of the next one

**Notes**

- When Mode 1 is selected, the field *delay value* must be superior or equal to the *minimal acquisition time*
- In Mode 2 there are no constraints on the delay value.

mode

2

time unit

s

delay value

2

 second(s)

minimal delay value

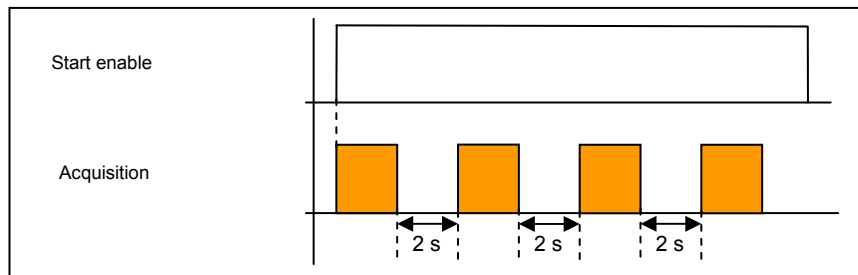
> 0

 second(s)



**Example**

After the start of the acquisition (see Fig. 5-12), the delay between the end and the start of the individual sequences is 2 s.



## 5.2.4 “Number of sequences to acquire”

**Fig. 5-11: Analog inputs: Number of sequences to acquire**

**Number of sequences to acquire**  
Please choose how many sequences must be run.

**Notes**

- Choose 0 for a continuous acquisition
- The maximum value for this field is  $2^{32}-1$  (4294967295)

sequences to acquire  
Please indicate the maximum number of sequences to acquire before the data are sent on the network.

**Notes**

- The minimum legal value for this field is 1.
- This is only a hint given to the system. If the storage capacity does not enable to keep the requested amount of data it will be sent sooner.

sequences before sending

In the field “sequences to acquire”, you enter the number of sequences to be acquired. If this value is 0, the acquisition is continuous. If it is a value between 1 and 4294967295, the number of sequences is predefined.

**Example**

To acquire four sequences, the field “sequences to acquire” must contain the value 4. As a result, when you start (“Start” button in the section “Start/stop acquisition”, see the following figure) four sequences are acquired.

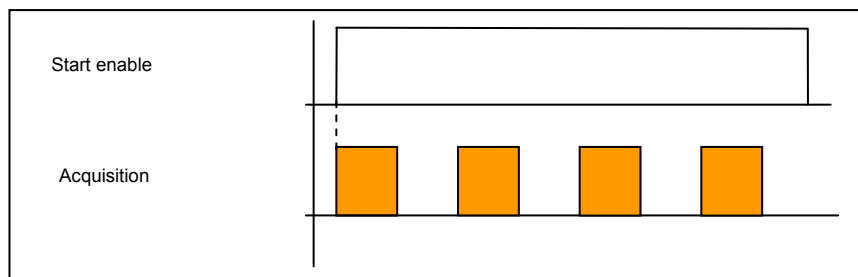
Fig. 5-12: Analog inputs: Start/stop acquisition

**Start/stop acquisition**

The **Start** button first stops any current running acquisition and then starts an acquisition as defined on this page.

The **Stop** button stops any currently running acquisition.

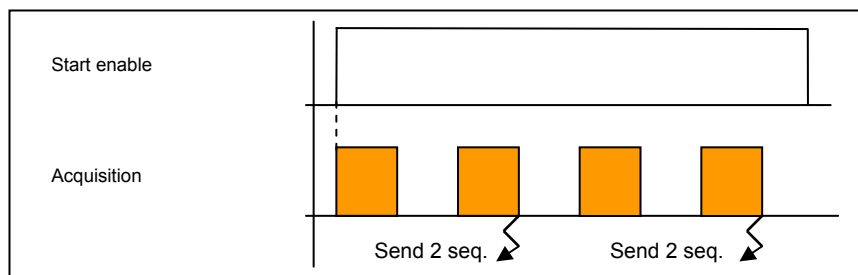
[Start](#) [Stop](#)



In the field “sequences before sending”, you define the maximum number of sequences that have to be acquired before the measurement values are sent to the target system. If the MSX-E system does not have sufficient memory to store the required number of sequences, the measurement values are sent earlier, that is, before the maximum number of sequences to be acquired is reached. This helps to reduce the network traffic load and the CPU resources of the MSX-E systems.

**Example**

When you start (see Fig. 5-12), the acquisition begins. If two sequences are acquired, the measurement values are sent to the client.



## 5.3 Common functions

The following functions are available both in Auto-refresh mode and in Sequence mode.

### 5.3.1 “Conversion time” (settling time)

**Fig. 5-13: Analog inputs: Conversion time**

**Conversion time**

The **Conversion Time** sets the switching time from channel to channel.

The **conversion time unit** specifies which base time unit is to be used (microsecond or millisecond)

Depending on the conversion time unit the range allowed for the Conversion Time varies:

- from 10 to 65535 when the unit is the microsecond
- from 1 to 65535 when the unit is the millisecond

set the conversion time

**Notes**

This parameter has no influence if only one channel is selected below.

In this section, the settling time is set, i.e. the time required to switch from one channel to another. As the unit of the settling time, microseconds, milliseconds or seconds can be defined. The range in which this time can lie is based on the unit that is selected:

**Microseconds:** 10 to 65535  
**Milliseconds:** 1 to 65535  
**Seconds:** 1 to 65535

If only one channel is selected, this parameter is insignificant.

### 5.3.2 “Minimal acquisition time”

**Fig. 5-14: Analog inputs: Minimal acquisition time**

**Minimal acquisition time**

This is a computed value and henceforth read-only.

(µs)

The duration of the acquisition is calculated automatically.

**Sequence mode: Calculation of the acquisition time**

As already mentioned in Chapter 3, the **MSX-E3011** or **MSX-E3021** has four 4-channel multiplexers. Consequently, the selected channels are not always acquired simultaneously in an acquisition in Sequence mode.

**NOTICE!**

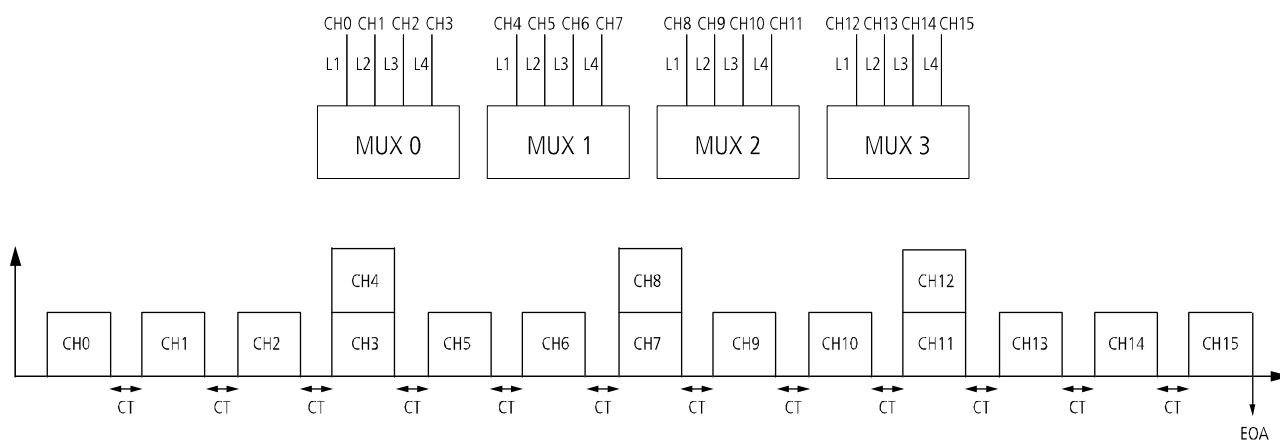
The calculation of the acquisition time depends on the way the channels are acquired: simultaneously or individually.

**Example 1**

The MSX-E system acquires 16 channels (CH0 to CH15) in this order:

CH0, CH1, CH2, CH3, CH4, CH5, CH6, CH7, CH8, CH9, CH10, CH11, CH12, CH13, CH14, CH15.

Line 4 of multiplexer 0 is connected in parallel to line 1 of multiplexer 1, line 4 of multiplexer 1 in parallel to line 1 of multiplexer 2 and line 4 of multiplexer 2 in parallel to line 1 of multiplexer 3.



CH = Channel

CT = Settling time

L = Line

EOA = End of acquisition

MUX = Multiplexer

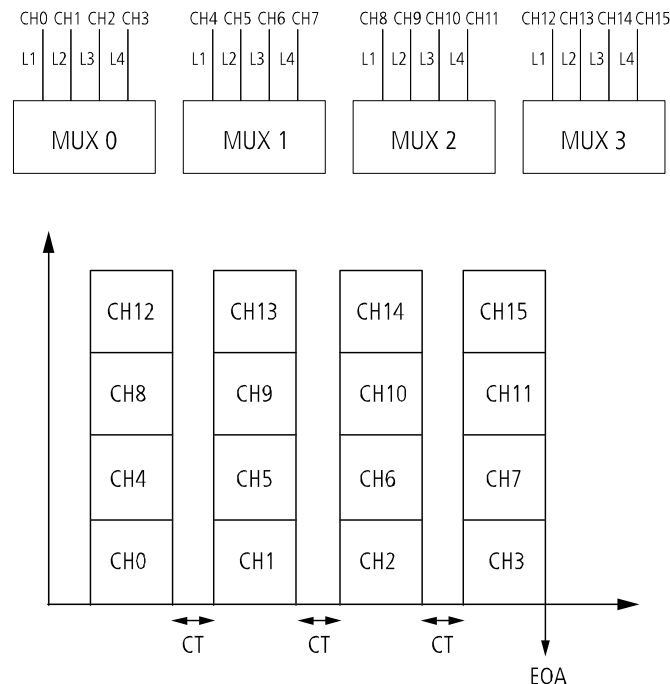
The two channels of the channel pairs CH3 and CH4, CH7 and CH8 as well as CH11 and CH12 are acquired simultaneously (CH3 and CH4 acquisition time = settling time \* 1). The other channels are acquired individually (CH0 to CH2 acquisition time = settling time \* 3, CH5 and CH6 acquisition time = settling time \* 2). This results in the following calculation: CH0 to CH15 acquisition time = settling time \* 13

**Example 2**

The MSX-E system acquires 16 channels (CH0 to CH15) in this order:

CH0, CH4, CH8, CH12, CH1, CH5, CH9, CH13, CH2, CH6, CH10, CH14, CH3, CH7, CH11, CH15.

The corresponding multiplexer lines 1 to 4 of multiplexers 0 to 3 are connected in parallel, i.e. line 1 of multiplexer 0 is connected in parallel to each line 1 of the other three multiplexers, line 2 in parallel to each line 2, etc.



CH = Channel  
L = Line  
MUX = Multiplexer  
CT = Settling time  
EOA = End of acquisition

CH0, CH4, CH8 and CH12 are acquired simultaneously (acquisition time = settling time \* 1). With the other three groups with four channels each, the channels are also acquired simultaneously per group. This results in the following calculation: CH0 to CH15 acquisition time = settling time \* 4

### 5.3.3 “Configure polarity”

**Fig. 5-15: Analog inputs: Configure polarity**

**Configure polarity**

Please select the polarity for the channels above.

**Notes**  
The new configuration will be only applied to those channels that were selected

- **unipolar** means the input is in a positive range (0V/+10V, 0/max20mA or 0V/+5V, 0/20mA depending of the selected gain).
- **bipolar** means the input includes a negative range (-10V/+10V, max-20/max+20mA or -5V/+5V, -20/+20mA depending of the selected gain)

1	2	3	4	5	6	7	8	9	10
Bipolar	Bipolar	Bipolar	Bipolar	Bipolar	Bipolar	Bipolar	Bipolar	Bipolar	Bipolar

For each channel that is selected, you can define the polarity.

“Unipolar” means that the MSX-E system measures only the values in the positive range from 0 V or 0 A. With “Bipolar”, also the values in the negative range are measured. The size of each relevant measurement area depends on the selected gain (see the following chapter).

## 5.3.4 “Configure gain”

Fig. 5-16: Analog inputs: Configure gain

**Configure gain**

Please select the gain for the channels above.

Note that even if this form allows you to select a configuration for a channel that was not selected for the acquisition, the new configuration will be only applied to those channels that were selected.

Please note that a gain of 2 is **recommended** for a channel of type current.

Selection,	when channel is unipolar,		when channel is bipolar	
1	0/+10 Volts or 0/ max 20 mA		+/- 10 Volts or +/- 20 mA max	
2	0/+5 Volts or 0/20 mA		+/- 5 Volts or +/- 20 mA	

1

2

3

4

5

6

7

8

9

10

11

12

13

14

15

16

The gain enables the measurement to be adapted to the input voltage range or input current range to achieve greater precision. Two gain types are available. The size of each measurement range depends on the gain and the polarity:

**Gain 1 unipolar:** 0 V to +10 V or 0 mA to 20 mA  
**bipolar:** -10 V to +10 V or -20 mA to +20 mA  
**Gain 2 unipolar:** 0 V to +5 V or 0 mA to 20 mA  
**bipolar:** -5 V to +5 V or -20 mA to +20 mA

**Example**

Gain 1 in unipolar 16-bit:

$(10 / 65535) = 1 \text{ bit}$  (corresponds to approx. 0.0001525 V)

Gain 2 in unipolar 16-bit:

$(5 / 65535) = 1 \text{ bit}$  (corresponds to approx. 0.00007695 V)

**NOTICE!**

For current measurements, gain 2 should be used.

### 5.3.5 Trigger configuration

The acquisition can be started by an external signal.

The synchro trigger configuration has to be set both on the master's and slave's web interface.

**Fig. 5-17: Analog inputs: Trigger configuration**

#### Trigger configuration

You can start the acquisition by a trigger in both auto refresh and sequence modes.

The **source** of the trigger may be **hardware** (from the digital input), or **synchro**, meaning through the inter-module synchronisation mechanism.

The hardware trigger can react to a **rising** edge, **falling** edge, or **both** edges.

It is possible to:

- initialise a **filter** on the trigger input to avoid errors
- define a number of edges before a trigger action is generated

There are two trigger modes:

**One shot**  
After the software is started, the module waits for a trigger signal to start the acquisition; afterward the trigger signal is ignored.

**Sequence**  
After the software is started, the module waits for the trigger signal and acquires x sequences (x is also adjustable) and waits again.

**Notes:**

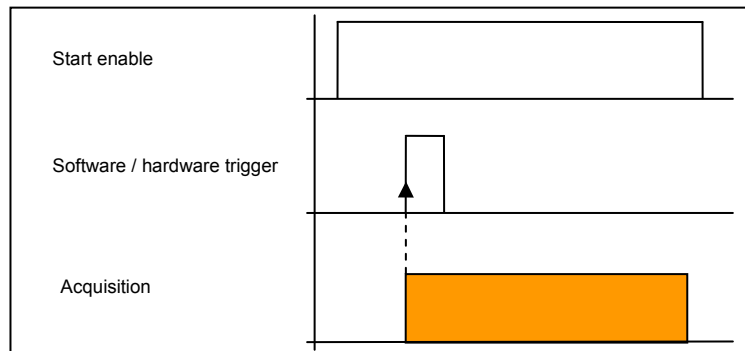
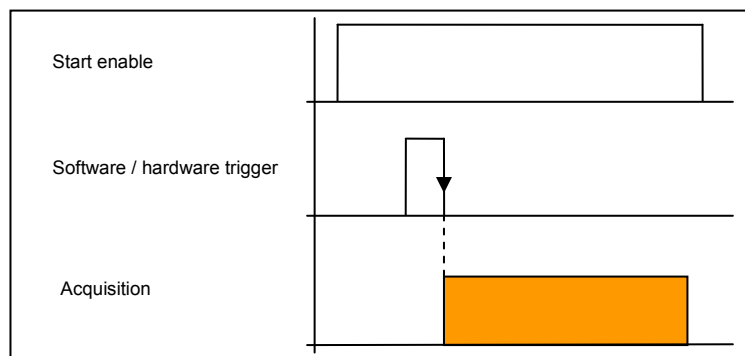
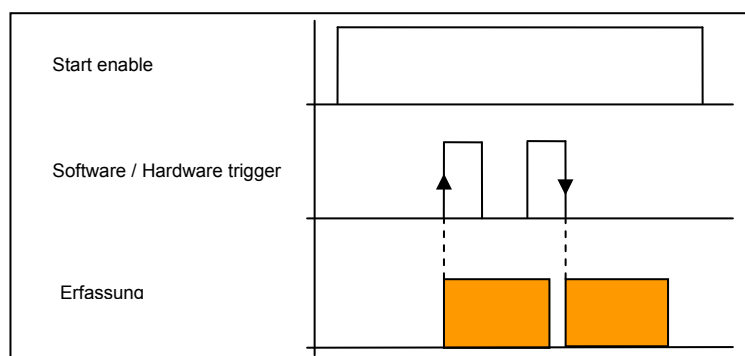
- The field *Trigger source* corresponds to "Trigger mask" in programming API.
- The field *Trigger mode* is **mandatory** when a trigger is selected
- The fields *Hardware trigger active edge* and *Hardware trigger count* are **not pertinent** when the synchro trigger is selected.
- The field *Hardware trigger count* can contain a value between **1** and **65535**.
- The field *Number of sequences per trigger* can contain a value between **1** and **65535**.
- The field *Number of sequences per trigger* is **not pertinent** when the mode *one-shot* is selected.
- The field *Number of sequences per trigger* is **mandatory** when the mode *sequence* is selected.

Trigger source	Trigger mode	Hardware trigger active edge	Hardware trigger count	Number of sequences per trigger
			number of trigger events before the acquisition starts.	number of sequences to acquire at each trigger event.
hardware	one-shot	rising	1	1 (sequences)

- **Trigger source:** Available trigger types are hardware trigger and synchro trigger.
- **Trigger mode:** If the trigger mode "One-shot" is selected, only one acquisition starts after a trigger. If the option "Sequence" (= "multi-shot") is activated, a defined number of acquisitions starts (see field "Number of sequences per trigger").
- **Hardware trigger active edge:** Here, the type of edge is defined in case of which the MSX-E system identifies a trigger.
- **Hardware trigger count:** This field defines the number of edges after which an acquisition is started.
- **Number of sequences per trigger:** In the trigger mode "Sequence" (see field "Trigger mode"), the number of sequences that are acquired after a trigger is defined. This value must be between 1 and 65535.

The following pages contain examples of the hardware trigger.

For further information on the hardware or synchro trigger, please refer to the general manual of the MSX-E systems (see PDF link).

**1) Examples of edges****a) Rising:** Rising edge**b) Falling:** Falling edge**c) Both:** Rising and falling edges



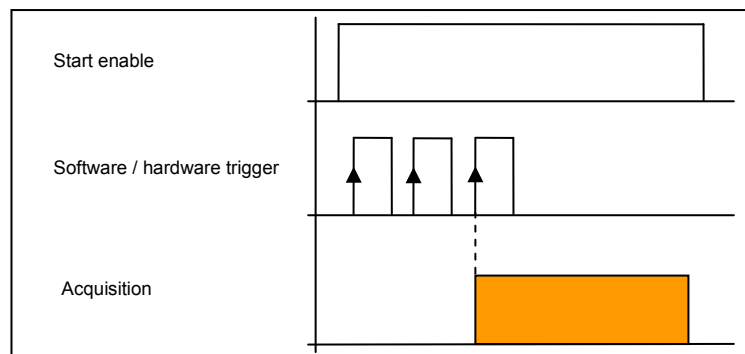
## 2) Examples of hardware triggers with “One-shot”

- a) To start the acquisition once only after three rising edges, you can use the following parameters:

**Fig. 5-18: Hardware trigger with “One-Shot” (a)**

Trigger source	Hardware trigger
Trigger mode	One-shot
Hardware trigger active edge	Rising
Hardware trigger count Number of trigger events before the acquisition starts.	3
Number of sequences per trigger Number of sequences to be acquired after each trigger event	1

After the start (see Fig. 5-12), the MSX-E system waits for three rising hardware edges. Once the three edges have been identified, the acquisition starts.

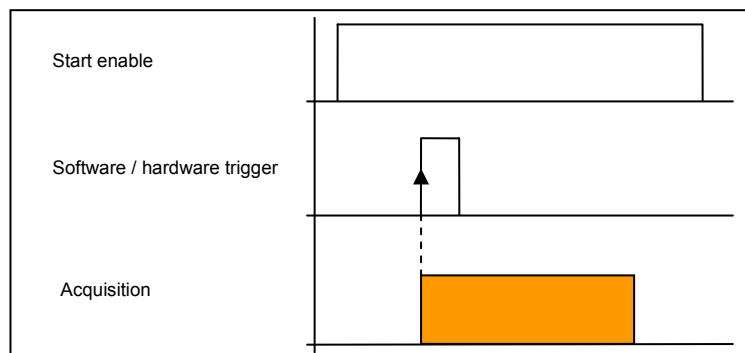


- b) With “Hardware trigger active edge”, “Rising” is selected again, and with “Hardware trigger count”, the value 1 is entered.

**Fig. 5-19: Hardware trigger with “One-Shot” (b)**

Trigger source	Hardware trigger
Trigger mode	One-shot
Hardware trigger active edge	Rising
Hardware trigger count Number of trigger events before the acquisition starts.	1
Number of sequences per trigger Number of sequences to be acquired after each trigger event	1

The trigger starts only one acquisition, which begins with the first hardware edge after you start (see Fig. 5-12).

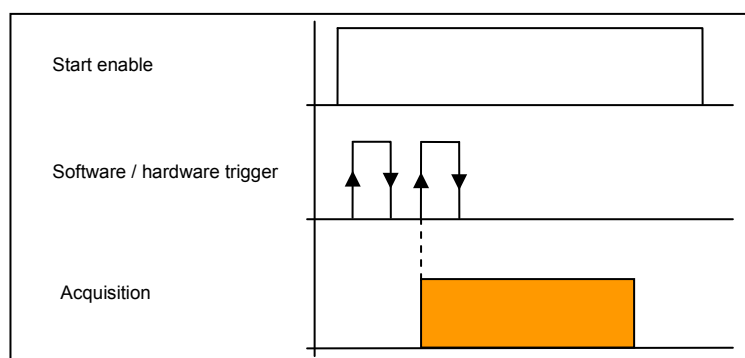


- c) With "Hardware trigger active edge", "Both" is selected, and with "Hardware trigger count", the value 3 is entered.

**Fig. 5-20: Hardware trigger with "One-Shot" (c)**

Trigger source	Hardware trigger
Trigger mode	One-shot
Hardware trigger active edge	Both
Hardware trigger count Number of trigger events before the acquisition starts.	3
Number of sequences per trigger Number of sequences to be acquired after each trigger event	1

After the start (see Fig. 5-12), the MSX-E system waits for three rising and falling hardware edges. Once the three edges have been identified, the acquisition starts.

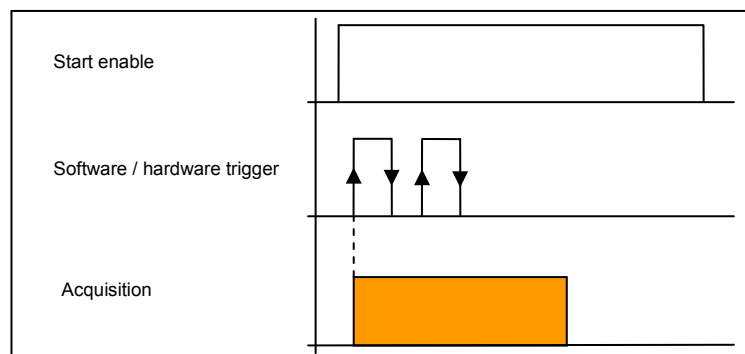


- d) With "Hardware trigger active edge", the option "Both" is selected again, and with "Hardware trigger count", the value 1 is entered.

**Fig. 5-21: Hardware trigger with "One-Shot" (d)**

Trigger source	Hardware trigger ▼
Trigger mode	One-shot ▼
Hardware trigger active edge	Both ▼
Hardware trigger count Number of trigger events before the acquisition starts.	1
Number of sequences per trigger Number of sequences to be acquired after each trigger event	1

If several edges occur after you start (see Fig. 5-12), the acquisition is started (triggered) with the first edge. The subsequent edges are ignored.

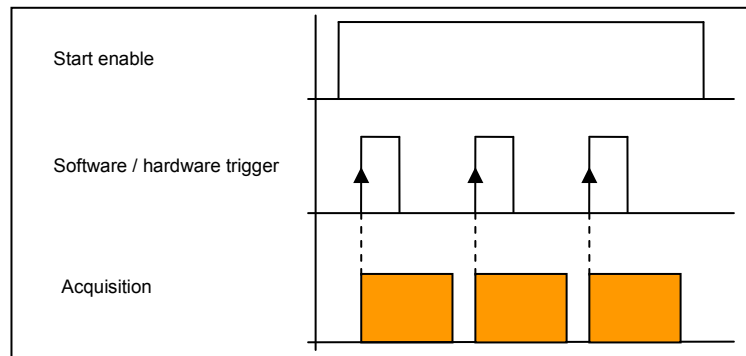


### 3) Examples of hardware triggers with "Sequence"

- a) To start each acquisition after one rising edge, you can use the following parameters:

**Fig. 5-22: Hardware trigger with "Sequence" (a)**

Trigger source	Hardware trigger ▼
Trigger mode	Sequence ▼
Hardware trigger active edge	Rising ▼
Hardware trigger count Number of trigger events before the acquisition starts.	1
Number of sequences per trigger Number of sequences to be acquired after each trigger event	1

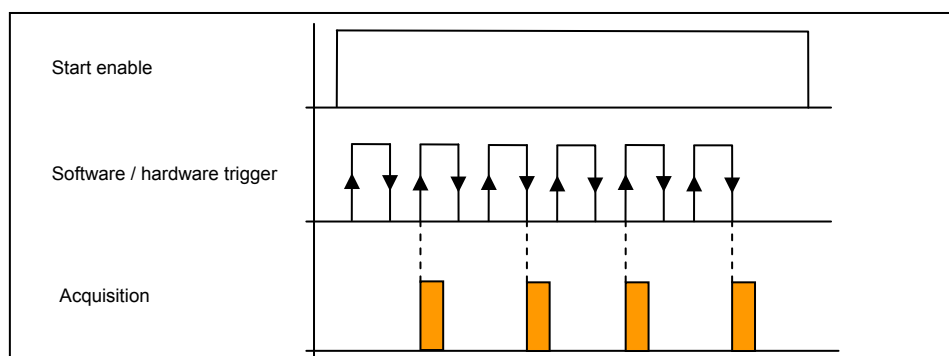


- b) With "Hardware trigger active edge", "Both" is selected, and "Hardware trigger count" contains the value 3.

**Fig. 5-23: Hardware trigger with "Sequence" (b)**

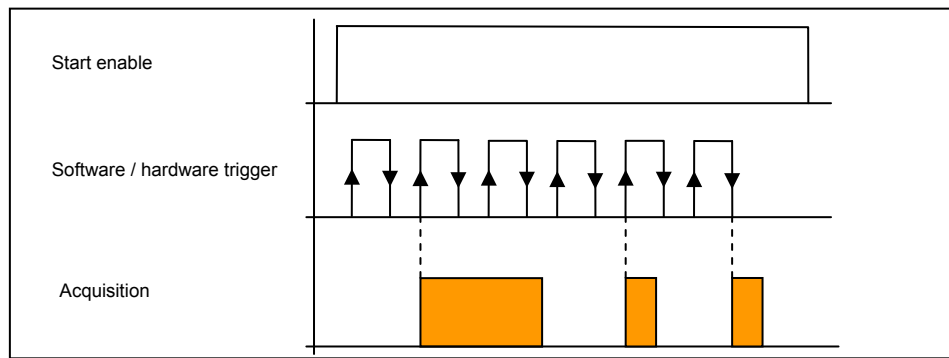
Trigger source	Hardware trigger
Trigger mode	Sequence
Hardware trigger active edge	Both
Hardware trigger count Number of trigger events before the acquisition starts.	3
Number of sequences per trigger Number of sequences to be acquired after each trigger event	1

After you start (see Fig. 5-12), the acquisition is started after three rising and falling edges. After the end of this sequence, the next sequence is started after three rising and falling edges, and so on.



### NOTICE!

Edges that occur during an acquisition are ignored. Only those edges are considered that occur after the end of an acquisition (see the previous and following examples).

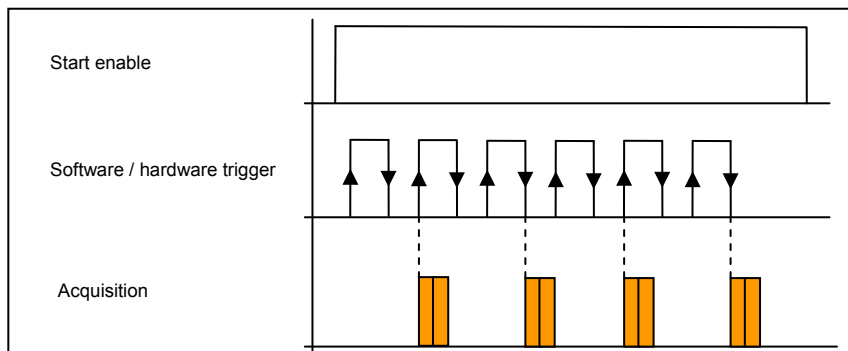


- c) The settings correspond to example 2 with the exception of "Number of sequences per trigger", where value 2 is entered.

**Fig. 5-24: Hardware trigger with "Sequence" (c)**

Trigger source	Hardware trigger
Trigger mode	Sequence
Hardware trigger active edge	Both
Hardware trigger count Number of trigger events before the acquisition starts.	3
Number of sequences per trigger Number of sequences to be acquired after each trigger event	2

After each trigger, two sequences are acquired.



### 5.3.6 “Other information in data packet” (additional data)

**Fig. 5-25: Analog inputs: Other information in data packet**

**Other information in data packet**

You can request the module to send a sequence counter with the data.

You can request to receive a time stamp with the data.

The result may be:

- sent as a digital value

☐ Send sequence counter  
☐ Send time stamp with data  
☐ Data in analog format

By default, only the acquisition values are sent to the client. However, it can also receive additional information if you activate the following options.

- **Send Auto-refresh (or Sequence counter):** The value of the Auto-refresh or Sequence counter is sent. In Auto-refresh mode, not all sequences are acquired so that the succession of the counter values is incomplete (e.g. 1, 3, 7). In Sequence mode, however, all sequences are acquired. Thus, the succession of these counter values is complete (1, 2, 3, etc.).
- **Send time stamp with data:** A time stamp is sent that contains the date of the acquisition.
- **Data in analog format:** With this option, the MSX-E system can convert the raw values immediately to the correct unit. This unit depends on the system type. With an **MSX-E3011** and an **MSX-E3021**, the unit is volts (V) or amperes (A). As the conversion affects the MSX-E CPU to a certain extent, this can result in slower sending speed.

### 5.3.7 “Binary data packet structure” (packet format)

**Fig. 5-26: Analog inputs: Binary data packet structure**

**Binary data packet structure**

To read the acquired data, the client connects to the data server network service via a TCP/IP socket. Data is sent encoded as little-endian integers logically grouped in packets. Depending on the configuration, other information may also be provided along, such as the auto refresh counter in auto refresh mode, the sequence counter in sequence mode and the time stamp in both modes.

The table below shows the structure of the binary packet according to the configuration presently active on this page.

channel 16	4 bytes
channel 5	4 bytes
channel 3	4 bytes
channel 11	4 bytes

size of a packet in bytes : 16

The MSX-E system sends the data over the network to one or more clients. In order that the client can interpret the values correctly, these are formatted. The format is defined as "Binary data frame packet structure". All measurement values and the additional data such as the time stamp form a group of values that is called a packet.

**NOTICE!**

The MSX-E system sends the packets in the Intel format (Little Endian).

For more information on the data format, see Chapter 4.1.2.

**Example**

A packet consists of a counter value and eight measurement values. The MSX-E system always sends one or more of these packets. The data client has to be programmed in such a way that it can receive a packet and interpret it correctly.

## 6 Technical data and limit values

### 6.1 Electromagnetic compatibility (EMC)

The Ethernet systems **MSX-E3011** and **MSX-E3021** comply with the European EMC directive. The tests were carried out by a certified EMC laboratory in accordance with the norm from the EN 61326 series (IEC 61326). The limit values as set out by the European EMC directive for an industrial environment are complied with.

The respective EMC test report is available on request.

### 6.2 Mechanical structure

Fig. 6-1: MSX-E3011 and MSX-E3021: Dimensions



Dimensions (L x W x H):	215 x 110 x 50 mm
Weight:	850 g 920 g (with MX-Rail)

Fig. 6-2: MSX-E3011 and MSX-E3021: View from above





**NOTICE!**

The connection lines must be installed in such a way that they are protected against mechanical loads.

## 6.3 Version

The specific version name can be found on the type label of your Ethernet system (see also Chapter 1.1 of the general MSX-E manual).

## 6.4 Limit values

Height:	2000 m over NN
Operating temperature:	<b>MSX-E3011:</b> -40 °C to +85 °C <b>MSX-E3021:</b> -25 °C to +85 °C
Storage temperature:	<b>MSX-E3011:</b> -40 °C to +85 °C <b>MSX-E3021:</b> -25 °C to +85 °C
Relative air humidity at indoor installation:	50 % at +40 °C 80 % at +31 °C (Ice formation from condensation must be prevented.)
<b>Current supply:</b>	
Nominal voltage:	24 VDC
Supply voltage:	18-30 V
Current consumption (at 24 V):	180 mA typ. (± 10 %)
<b>Safety:</b>	
Degree of protection:	IP 65 <sup>2</sup>
Optical isolation:	1000 V
Reverse polarity protection:	1 A max.

**NOTICE!**

After boot-up, the MSX-E system should warm up for a minimum 15 minutes so that a constant internal temperature will be reached.

### 6.4.1 Ethernet

Number of ports:	2
Optical isolation:	1000 V
Cable length:	150 m (max. for CAT5E UTP)
Bandwidth:	10 Mbps (auto-negotiation) 100 Mbps (auto-negotiation)
Protocol:	10 Base-T according to IEEE 802.3 100 Base-TX according to IEEE 802.3
MAC address:	00:0F:6C:##:##:## (unique for each device)

<sup>2</sup> The degree of protection is only provided when the relevant protection caps are used.

### 6.4.2 Trigger input

#### 24 V trigger input

Number of inputs:	1
Filter/Protective circuit:	low-pass/transorb diode
Optical isolation:	1000 V (via opto-couplers)
Nominal voltage:	24 VDC
Input voltage:	0-30 V
Input current:	11 mA typ. (at nominal voltage)
Max. input frequency:	2 MHz (at nominal voltage)
Logic input levels:	U <sub>Hmax</sub> : 30 V U <sub>Hmin</sub> : 19 V U <sub>Lmax</sub> : 14 V U <sub>Lmin</sub> : 0 V

#### 5 V trigger input (optional)

Number of inputs:	1
Filter/Protective circuit:	low-pass/transorb diode
Optical isolation:	1000 V (via opto-couplers)
Nominal voltage:	5 VDC
Input voltage:	0-5 V
Input current:	12 mA typ. (at nominal voltage)
Max. input frequency:	1 MHz (at nominal voltage)
Signal threshold:	2.2 V typ.

### 6.4.3 Synchro input and output

Number of inputs:	1
Number of outputs:	1
Optical isolation:	1000 V
Output type:	RS422
Driver level (master) V <sub>A-B</sub> :	≤ -1.5 V (low) ≥ 1.5 V (high)
Receiver level (slave) V <sub>A-B</sub> :	≤ -200 mV (low) ≥ 200 mV (high)

### 6.4.4 Analog inputs

Number of inputs:	16 (differential)
Architecture:	4 groups of 4 channels each (4-channel simultaneous converter with one 4-channel multiplexer per converter)
Resolution:	16-bit (bipolar) 15-bit (unipolar)
Precision:	± 1.221 mV typ. (± 4 LSB) ± 2.442 mV max.
Relative precision (INL):	± 3 LSB max. (ADC)

Optical isolation:	1000 V
Input ranges:	$\pm 5 \text{ V}$ , $\pm 10 \text{ V}$ (software-programmable)
Throughput rate:	25 kHz per channel or 100 kHz max. (if only 1 channel in each group is used)
Gain:	x1, x2 (software-programmable)
Common mode rejection:	80 dB min., DC up to 60 Hz (differential amplifier)
Input impedance (PGA):	$10^9 \Omega // 10\text{nF}$ relating to GND
Bandwidth (-3 dB):	160 kHz (limited by low-pass filter) 16 Hz (equipment option with differential filter)
Trigger:	a) software-programmable b) digital input c) synchro
Offset error:	$\pm 1 \text{ LSB}$ ( $\pm 305 \mu\text{V}$ )
Gain error:	$\pm 2.5 \text{ LSB}$
Temperature drift:	$2.3 (\mu\text{V/V}/^\circ\text{C}) * V_{\text{in}} + 22.5 (\mu\text{V}/^\circ\text{C})$ typ. $V_{\text{in}}$ : input voltage in V ( $-10 \text{ V} \leq V_{\text{in}} \leq +10 \text{ V}$ ) in the temperature range from $-40^\circ\text{C}$ to $+85^\circ\text{C}$ : 4.5 ppm/ $^\circ\text{C}$ FSR
<b>MSX-E3011-16-PC-Diff</b> (option)	
Shunt resistance:	250 $\Omega$ (0.01 % TC 25 ppm)
Calibration:	gain x2 ( $\pm 5 \text{ V}$ input range)

## 7 Appendix

### 7.1 Glossary

**Cascading**

Cascading means connecting multiple similar elements together to enhance their individual effect. The individual elements must be such that the outputs of a given element are compatible with the inputs of the subsequent element in terms of values and functionality.

**EMC**

= Electromagnetic Compatibility

The definition of the VDE regulation 0870 states: Electromagnetic compatibility is the ability of an electrical installation to function satisfactorily within its electromagnetic environment without unduly affecting its environment and the equipment it contains.

**FSR**

= Full Scale Range

FSR is the usable measurement range.

**Ground line**

Ground lines should not be seen as potential-free return lines. Different ground points may have small potential differences. This is always true with large currents and may cause inaccuracy in high-resolution circuits.

**IEC**

= International Electrotechnical Commission

The IEC is a UN body affiliated to the ISO (International Standards Organisation) which sets standards for electrotechnical parts and components.

**Input level**

The input level is the logarithmic ratio between two electrical values of the same type (voltage, current or power) at the signal input of any receiving unit. This unit is often configured as a logical level related to the input of the circuit.

The input voltage corresponding to logic "0" is between 0 V and 15 V and the voltage corresponding to logic "1" is between 17 V and 30 V.

**IP degree of protection**

The IP standard defines the degree of protection of a system against dirt and water. The first figure after the "IP" (e.g. 6 in IP 65) indicates the degree of protection against solid objects penetrating the housing. The second figure indicates the degree of protection against liquids penetrating the housing. In IP 65, the figures 6 and 5 have the following meaning: 6 = full protection against moving parts and against dirt penetration; 5 = protection against jets of water from any direction.

In IP 40, the figure 4 equates to protection against contact with small objects and protection against small foreign bodies (larger than 1 mm). The figure 0 means that there is no protection.

**Level**

Logic levels are defined for processing and displaying information.

In binary switches, voltages are used for digital values. Here, the two voltage ranges "H" (high) and "L" (low) represent the information.

The "H" range is closer to plus infinity; the "H" level corresponds to digital 1. "L" denotes the range closer to minus infinity; the "L" level corresponds to digital 0.

**Limit value**

Exceeding the limit values, even for a short time, can easily result in the destruction of the component or the (temporary) loss of functionality.

**MAC address**

MAC = Media Access Control

This is the hardware address of network components used to identify them uniquely within the network.

**Protective circuit**

A protective circuit is set up on the actuator side to protect the control electronics and provide adequate EMC safety. The simplest protective circuit involves connecting a resistor in parallel.

**Resolution**

The resolution indicates how precisely a signal or value is held within the computer.

**SOAP**

= Simple Object Process Protocol

SOAP is a simple extensible protocol for exchanging information in distributed environments. It defines XML messages that can be exchanged between heterogeneous applications via HTTP. SOAP is independent of operating systems and can be integrated into existing Internet structures, including Ethernet TCP/IP-based automation concepts. SOAP is based on Remote Procedure Calls and XML. This means that functions from other platforms can be called and used from any point within the network. Any results data can also be returned using XML schemas. This enables distributed computing capacity and non-redundant data storage in distributed systems.

**TCP/IP**

= Transmission Control Protocol/Internet Protocol

TCP/IP is a family of network protocols and therefore often just referred to as Internet protocol. The computers that are part of the network are identified via their IP addresses. UDP is another transport protocol that belongs to the core group of this protocol family.

**Trigger**

A trigger is a pulse or signal for starting or stopping a special task. Triggers are often used for controlling data acquisition.

**UDP**

= User Datagram Protocol

This is a minimal connection-free network protocol which is part of the transport layer within the Internet protocol family. The purpose of UDPs is to ensure that data transmitted over the Internet reach the correct application.

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